

Motronic MS 2.8

The MS 2.8 is a highly sophisticated engine management system. The system layout is basically made for 6-cylinder engines. All internal power stages are designed with a diagnosis interface. Various engine and chassis parameters can be measured and logged. Four vibration sensor inputs allow knock detection and knock control. Injection time, injection end timing and ignition timing are calculated from basic maps and can be corrected by different engine parameters.



Injection timing Ignition timing Lambda control Boost control (option) Knock control Data acquisition

Mechanical data

| Dust and water proof aluminium housing | | |
|--|-------------------|--|
| Connectors in military technology | | |
| Each pin individually filtered | | |
| Vibration damped circuit boards | | |
| Flexible housing fixation points | | |
| Size with connectors | 194 x 245 x 51 mm | |
| Weight | 2068 g | |

Conditions for use

| ECU temperature | -40 75°C |
|----------------------------|--------------|
| Max. power consumption | 18 W at 14 V |
| Max. vibration | 15 g sinus |
| at 20 Hz 2 kHz for t < 5 h | |

Electronic data

In general 7 microcontrollers with 16 bit organisation; calculator capacity 50 MIPS Real time clock



Inputs

4 inputs for Ni-Cr-Ni exhaust gas temperature sensors 4 lambda LSM 11 interfaces 4 inputs for inductive wheel speed sensors (Hall optional) 42 universal inputs 0 ... 5 V 6 differential inputs ± 5 V 1 input for inductive or Hall crankshaft sensor 1 input for inductive or Hall camshaft sensor 4 inputs for knock sensors Outputs All power stages short circuit protected 6 high speed power stages (2A) for servo motor control 7 diagnosis signal outputs 12 peak and hold injection power stages with diagnosis interface 3 high current power stages (12 A) with diagnosis interface 6 ignition power stages with diagnosis interface 3 sensor supply 5 V/100 mA 3 sensor supply 10 V/200 mA **Communication interfaces** 2 RS232 interfaces for telemetry and laptrigger 1 2-Mbaud interface for memory data read out or high speed telemetry 3 CAN interfaces Memory 4 MB memory for data acquisition